L Number	Hits	Search Text	DB	Time stamp
2	33922	position adj detection	USPAT;	2004/03/01
			US-PGPUB;	
			EPO; JPO; DERWENT;	
			IBM TDB	
4	133957	linear near2 movement or rotational near2	USPAT;	2004/03/01
3	13330	movement	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
_			IBM_TDB	0004/00/01
5	951	(position adj detection) and (linear near2 movement or rotational near2 movement)	USPAT; US-PGPUB;	2004/03/01
		movement of focational nearz movement,	EPO; JPO;	
			DERWENT;	
			IBM TDB	
6	243	((position adj detection) and (linear	USPAT;	2004/03/01
		near2 movement or rotational near2	US-PGPUB;	
		movement)) and (absolut\$3 adj track\$3 or	EPO; JPO;	
		detect\$4 adj (unit or device))	DERWENT; IBM TDB	
7	91	(((position adj detection) and (linear	USPAT;	2004/03/01
	31	near2 movement or rotational near2	US-PGPUB;	2001,00,01
		movement)) and (absolut\$3 adj track\$3 or	EPO; JPO;	
		detect\$4 adj (unit or device))) and head\$1	DERWENT;	
10	625	//	IBM_TDB	2004/03/01
10	635	((position adj detection) and (linear near2 movement or rotational near2	USPAT; US-PGPUB;	2004/03/01
		movement)) and (absolut\$3 adj track\$3 or	EPO; JPO;	
		<pre>detect\$4 adj (unit or device or position))</pre>	DERWENT;	
			IBM_TDB	
11	155	, , , , , , , , , , , , , , , , , , , ,	USPAT;	2004/03/01
		near2 movement or rotational near2	US-PGPUB;	
		movement)) and (absolut\$3 adj track\$3 or detect\$4 adj (unit or device or	EPO; JPO; DERWENT;	
		position))) and (cod\$3)	IBM TDB	
1	28	absolut\$3 adj track\$3 and detect\$4 adj	USPAT;	2004/03/01
		(unit or device)	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
3	5	(position adj detection) and (absolut\$3	IBM_TDB USPAT:	2004/03/01
³	3	adj track\$3 and detect\$4 adj (unit or	US-PGPUB;	2004/03/01
		device))	EPO; JPO;	
			DERWENT;	
	_		IBM_TDB	000: 10= 1=
8	9	((((position adj detection) and (linear	USPAT; US-PGPUB;	2004/03/01
		near2 movement or rotational near2 movement)) and (absolut\$3 adj track\$3 or	EPO; JPO;	
		detect\$4 adj (unit or device))) and	DERWENT;	
		head\$1) and (cod\$3 and array\$3)	IBM_TDB	
9	17	((((position adj detection) and (linear	USPAT;	2004/03/01
		near2 movement or rotational near2	US-PGPUB;	
		movement)) and (absolut\$3 adj track\$3 or detect\$4 adj (unit or device))) and	EPO; JPO; DERWENT;	
		detect\$4 adj (unit or device))) and head\$1) and (cod\$3)	IBM TDB	
12	74	((((position adj detection) and (linear	USPAT;	2004/03/01
		near2 movement or rotational near2	US-PGPUB;	
		movement)) and (absolut\$3 adj track\$3 or	EPO; JPO;	
		detect\$4 adj (unit or device or	DERWENT;	
13	1022	position))) and (cod\$3)) and head\$1 (maximum or maximal) adj1 length near1	IBM_TDB USPAT;	2004/03/01
	1022	sequence	US-PGPUB;	2004/03/01
			EPO; JPO;	1
			DERWENT;	1
			IBM_TDB	
14	209	((maximum or maximal) adjl length nearl	USPAT;	2004/03/01

((maximum or maximal) adjl length nearl sequence) and polynomial $\ensuremath{\mathsf{N}}$

2004/03/01 13:48

USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB

15	142	(((maximum or maximal) adjl length nearl	USPAT;	2004/03/01 13:48
		sequence) and polynomial) and detect\$3	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM TDB	
16	30	((((maximum or maximal) adj1 length near1	USPAT;	2004/03/01 13:56
		sequence) and polynomial) and detect\$3)	US-PGPUB;	
		and absolut\$3	EPO; JPO;	
			DERWENT;	
			IBM TDB	
17	112	((((maximum or maximal) adj1 length near1	USPAT;	2004/03/01 13:57
		sequence) and polynomial) and detect\$3)	US-PGPUB;	}
		not (((((maximum or maximal) adj1 length	EPO; JPO;	
		nearl sequence) and polynomial) and	DERWENT;	
		detect\$3) and absolut\$3)	IBM_TDB	